

EDGE AND FOG COMPUTING FOR CAVs



Autonomous Vehicles: The Vision



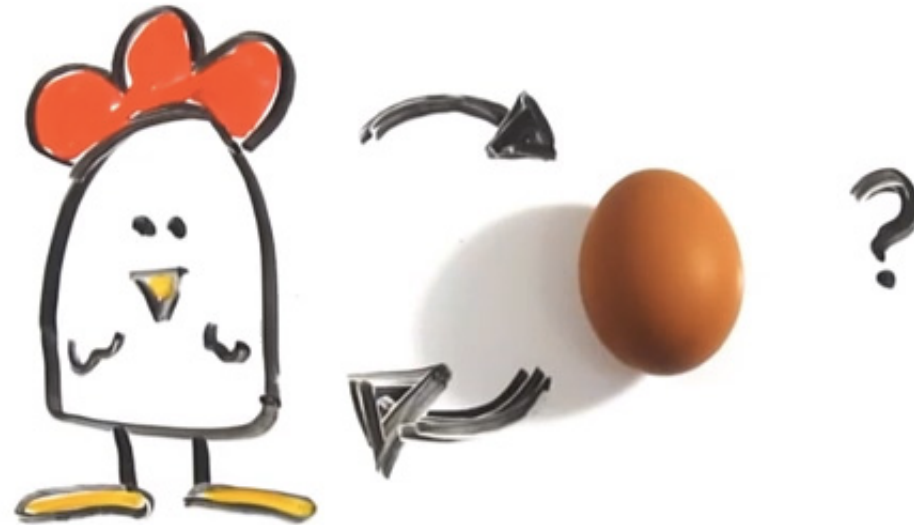
Autonomous Vehicles: The Reality



Edge and Fog Computing: Solving the CAV Goldilocks Dilemma



Edge and Fog Computing: Solving the Chicken or the Egg Dilemma



Edge and Fog Computing for CAV's

Challenge

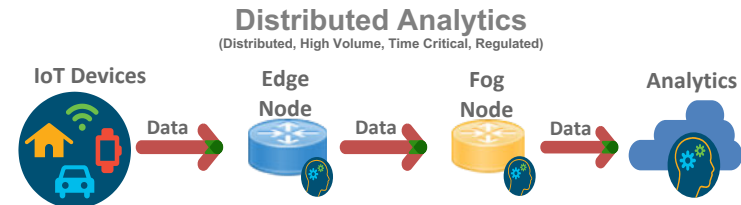
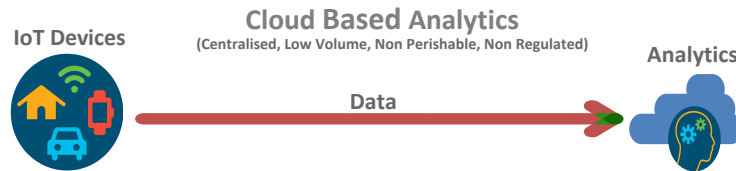
Vehicle-centric Connected Autonomous Vehicle (CAV) applications are challenged in a number of areas:

- sensor fidelity, especially in detecting vulnerable road users
- realising CAV benefits while CAV deployments are low
- scalable data management for CAVs and intelligent transport systems (ITS)

Solution

It is possible to address these issues by using infrastructure-centric CAV applications combined with real-time data from multiple sources and processed as close to the data source as possible (infrastructure such as at intersections) leading to:

- earlier detection of impending events and notification
- better protection for vulnerable roads users
- immediate benefits for early adopters
- efficient data collection and management.



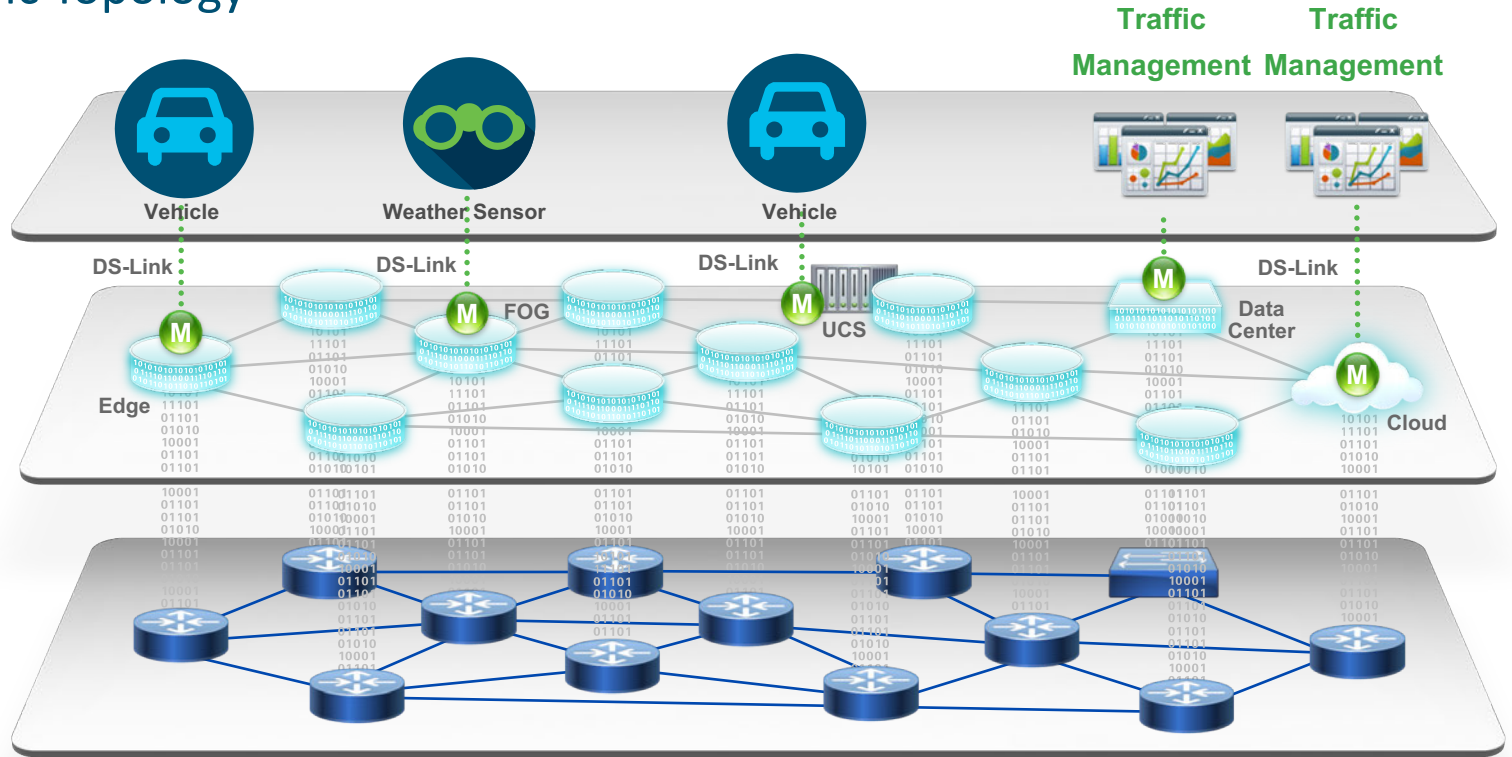
Edge and Fog Computing for CAV's

Data Fabric Topology

Enabling
Applications &
Microservices

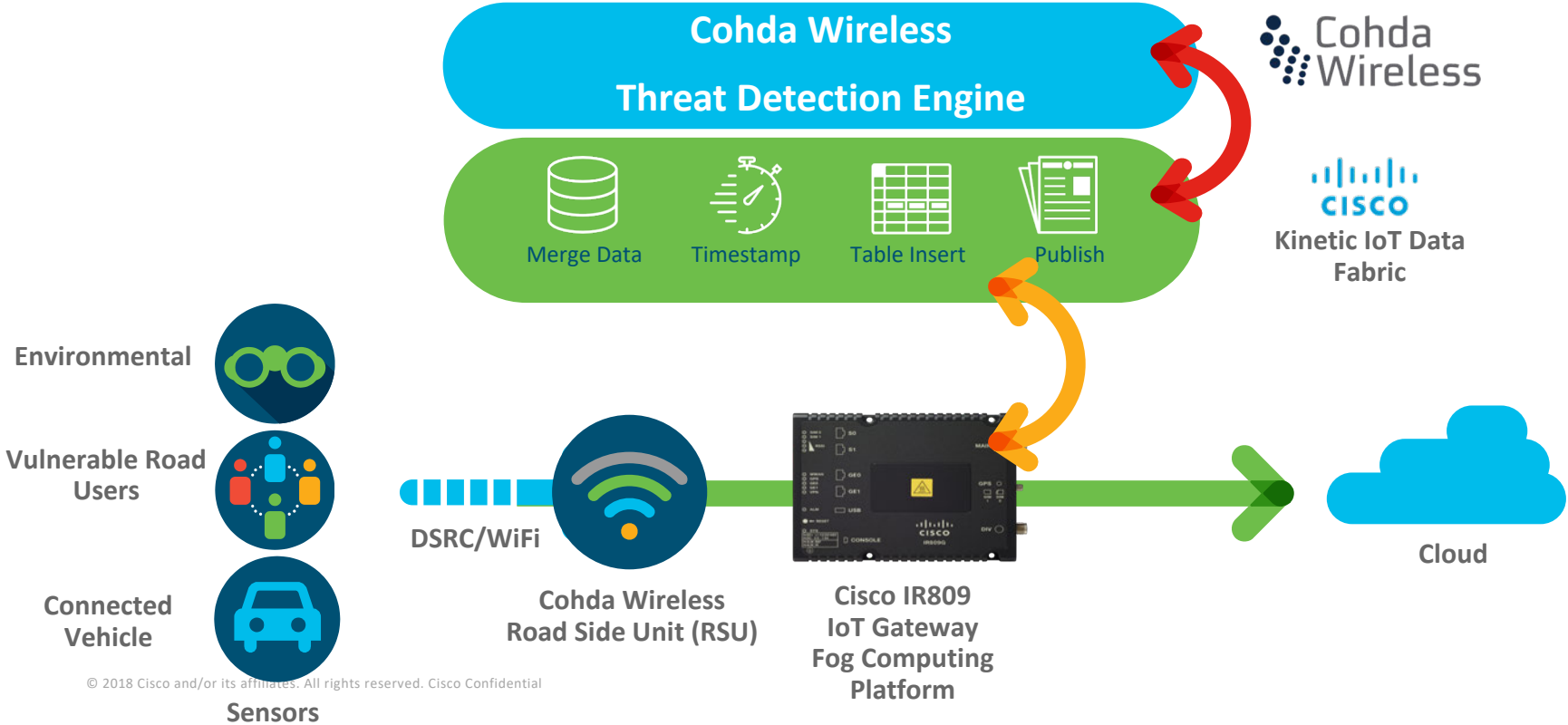
IoT Data
Fabric

IoT Network
Fabric



Edge and Fog Computing for CAV's

Intersection Topology



Deploying Edge & Fog Computing

Use Case 1: Dynamic Speed Management



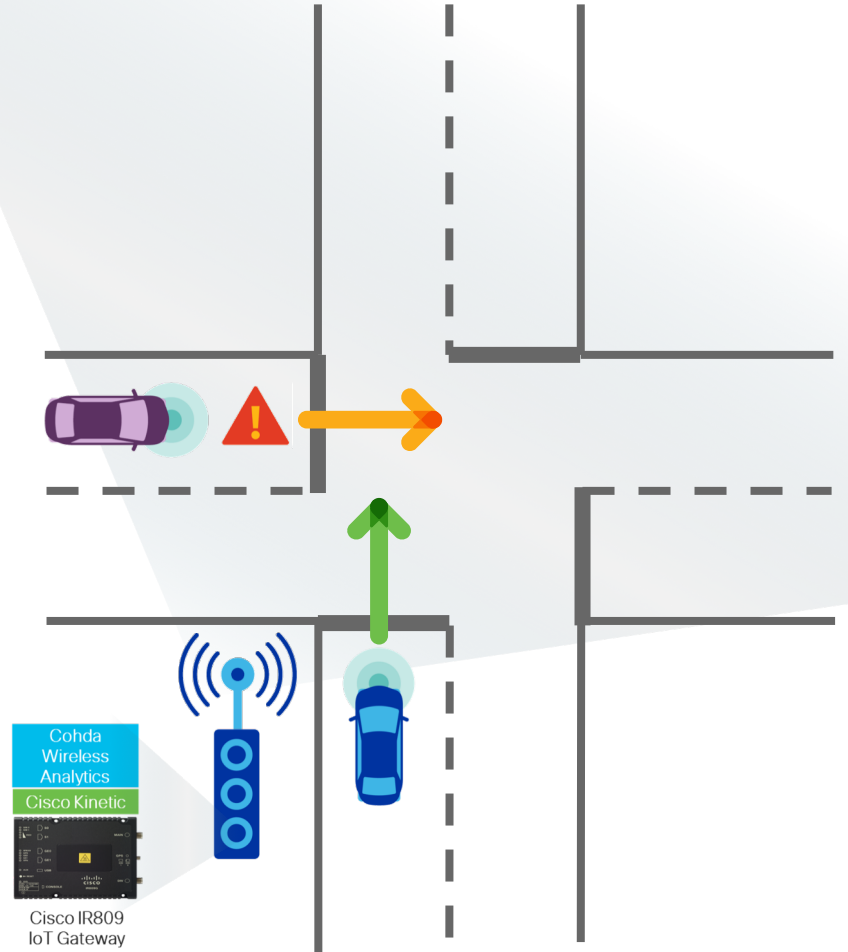
Deploying Edge & Fog Computing

Use Case 2: Vulnerable Road User Protection



Deploying Edge & Fog Computing

Use Case 3: Intersection Collision Avoidance



**Reduces Latency
for Time-Sensitive
Applications**

Enables New Data Insights

**Accelerates Safety Benefits Including
Protecting Vulnerable Road Users**



**Edge & Fog
Computing
For CAVs**

